

APPLICATION
FOR
UNITED STATES LETTERS PATENT

TITLE: VISION PROSTHESIS

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CERTIFICATE OF MAILING BY EXPRESS MAIL

Express Mail Label No. EV 303681822 US

July 25, 2003
Date of Deposit

VISION PROSTHESIS

FIELD OF INVENTION

This invention relates to a vision prosthesis, and in particular, to prosthetic lenses.

BACKGROUND

5 In the course of daily life, one typically regards objects located at different distances from the eye. To selectively focus on such objects, the focal length of the eye's lens must change. In a healthy eye, this is achieved through the contraction of a ciliary muscle that is mechanically coupled to the lens. To the extent that the ciliary muscle contracts, it deforms the lens. This deformation changes the focal length of the lens. By
10 selectively deforming the lens in this manner, it becomes possible to focus on objects that are at different distances from the eye. This process of selectively focusing on objects at different distances is referred to as "accommodation".

As a person ages, the lens loses plasticity. As a result, it becomes increasingly difficult to deform the lens sufficiently to focus on objects at different distances. To
15 compensate for this loss of function, it is necessary to provide different optical corrections for focusing on objects at different distances.

One approach to applying different optical corrections is to carry different pairs of glasses and to swap glasses as the need arises. For example, one might carry reading glasses for reading and a separate pair of distance glasses for driving. This is
20 inconvenient both because of the need to carry more than one pair of glasses and because of the need to swap glasses frequently.

Bifocal lenses assist accommodation by integrating two different optical corrections onto the same lens. The lower part of the lens is ground to provide a correction suitable for reading or other close-up work while the remainder of the lens is
25 ground to provide a correction for distance vision. To regard an object, a wearer of a bifocal lens need only maneuver the head so that rays extending between the object-of-regard and the pupil pass through that portion of the bifocal lens having an optical correction appropriate for the range to that object.

The concept of a bifocal lens, in which different optical corrections are integrated into the same lens, has been generalized to include trifocal lenses, in which three different optical corrections are integrated into the same lens, and continuous gradient lenses in which a continuum of optical corrections are integrated into the same lens. However, just
 5 as in the case of bifocal lenses, optical correction for different ranges of distance using these multifocal lenses relies extensively on relative motion between the pupil and the lens.

Once a lens is implanted in the eye, the lens and the pupil move together as a unit. Thus, no matter how the patient's head is tilted, rays extending between the object-of-
 10 regard and the pupil cannot be made to pass through a selected portion of the implanted lens. As a result, multifocal lenses are generally unsuitable for intraocular implantation because once the lens is implanted into the eye, there can be no longer be relative motion between the lens and the pupil.

A lens suitable for intraocular implantation is therefore generally restricted to
 15 being a single focus lens. Such a lens can provide optical correction for only a single range of distances. A patient who has had such a lens implanted into the eye must therefore continue to wear glasses to provide optical corrections for those distances that are not accommodated by the intraocular lens.

SUMMARY

20 The invention provides a vision prosthesis for restoring a patient's ability to focus on objects at different distances. The vision prosthesis includes a lens whose focal length can automatically be changed, and a rangefinder coupled to that lens for estimating the range to an object that the patient wishes to focus on.

In one embodiment, the variable-focus lens of the vision prosthesis has an index
 25 of refraction that varies in response to a focusing stimulus. An actuator in communication with the lens provides the necessary focusing stimulus on the basis of a range estimate from the rangefinder. A controller coupled to the rangefinder and to the actuator causes the actuator to generate a focusing stimulus on the basis of this range estimate.

Because it is the index of refraction that is changed, the vision prosthesis provides control over the focal length of the lens without the need to mechanically move the lens or any portions thereof. The vision prosthesis thus provides a lens of variable focal length with no moving parts and without the complexity and excessive power consumption
5 associated with a moveable system.

The lens of the vision prosthesis can be adapted for implantation in an eye of a phakic or an aphakic human patient. Alternatively, the lens, and its associated electronics, can be worn outside the patient on, for example, an eyeglass frame.

When implanted in the eye, the lens can be disposed at a variety of locations, such
10 as the anterior chamber, the posterior chamber, the lens bag, or the cornea. To ease the implantation process and to minimize the extent of the incision required, the lens can be a foldable lens having a tendency to spring back into an unfolded state.

In one embodiment of the vision prosthesis, the lens includes a chamber containing a nematic liquid crystal or other material that has a changeable index of
15 refraction. A nematic liquid crystal has an index of refraction that changes in response to an applied electromagnetic field. This change in the index of refraction results in a change in the focal length of the lens.

The actuator for the lens can include a variable voltage source and one or more electrodes coupled to both the variable voltage source and the lens. Alternatively, the
20 actuator can include a variable current source and one or more coils coupled to the variable current source and to the lens. In either case, the actuator generates a field, an electric field in the former case and a magnetic field in the latter case, that can interact with the nematic liquid crystal to selectively alter its index of refraction.

The index of refraction of the lens need not be spatially uniform. By providing a
25 plurality of actuating elements coupled to different local regions of the lens, the index of refraction can be varied at those local regions. This enables the lens to have an effective optical shape that is largely independent of its physical shape. A convex lens can be created, for example, by applying a stronger electric field to the central portion of a

planar chamber filled with nematic liquid crystal than to the periphery. This changes the index of refraction at the center more than at the periphery. A lens having a spatially non-uniform index of refraction can be implemented by providing a plurality of electrodes disposed at different portions of the lens. In one aspect of the invention, these electrodes
5 are concentric electrodes. In such a case, the index of refraction can be made a function of distance from the center of the lens.

In an alternative embodiment, the index of refraction can be made a function of more than one spatial variable. For example, the electrodes can be distributed in a two-dimensional grid on the surface of the lens. Such a grid can be a polar grid or a rectilinear
10 grid. Its primary function would be to correct wavefront aberrations present in the eye due to abnormalities in the cornea, the lens, and the ocular media.

An advantage of a lens having planar chamber as described above is that such a lens can be made thin enough to be implanted in very small spaces within the eye. For example, a lens in which first and second planar sides are separated by a gap smaller than
15 the separation between the lens bag in an eye and the iris in the eye can be implanted in the posterior chamber of the eye.

In some cases, it may not be possible to vary the index of refraction sufficiently to correct the patient's vision. In such cases, the lens can include one or more lens elements that can be moved so as to bring an image into focus. Such a lens also includes a motor to
20 move the lens elements.

Alternatively, the lens can have a baseline curvature and also be filled with nematic crystal or a material having an index of refraction that can be changed. The baseline curvature can be used to perform a gross correction that can be fine-tuned by locally varying the index of refraction of the lens material.

25 In one embodiment of the vision prosthesis, the rangefinder includes a transducer for detecting a stimulus from an anatomic structure in an eye, the stimulus being indicative of a range to the object-of-regard. The transducer can be a pressure transducer for detecting contraction of a muscle, such as a piezoelectric element that generates a

voltage in response to contraction of the muscle. Alternatively, the transducer can be an electromyograph for detecting electrical activity associated with contraction of the muscle.

5 The stimulus detected by the transducer can come from the activities or states of one or more anatomical structures within the eye. These activities or states include: contraction of a ciliary muscle, tension in a zonule, mechanical disturbance of a lens bag, contraction of a rectus muscle, and dilation of an iris.

10 The rangefinder of the vision prosthesis does not, however, have to rely on the operation of any structure in eye to estimate a distance to an object. For example, the rangefinder can also include an autofocus system. One example of an autofocus system includes: an infrared transmitter for illuminating an object with an infrared beam; an infrared receiver for receiving a reflected beam from the object, and a processor coupled to the infrared receiver for estimating a range to the object on the basis of the reflected beam. However, other autofocus systems can readily be adapted for the use in the
15 vision prosthesis.

To assist the autofocus system in achieving and maintaining focus, it is often desirable to include a feedback loop coupled to the autofocus system. One example of a feedback loop includes first and second lenslets posterior to the lens. Each lenslet is in optical communication with an associated photodetector posterior to that lenslet. The
20 distance between the lenslet and its associated photodetector is between the focal lengths of the two lenslets.

Regardless of the type of rangefinder, it is useful to provide an optional manual focusing control for enabling a patient to fine tune focusing of the lens. A manual focusing control enables the patient to correct compensate for minor inaccuracies in the
25 signal provided by the automatic focusing system. With a manual focusing control, the rangefinder can in fact be dispensed with. Thus, in yet another embodiment of the invention, the apparatus includes a manual focusing control instead of a rangefinder.

These and other features and advantages of the invention will be apparent from

the following detailed description and the accompanying figures, in which:

BRIEF DESCRIPTION OF THE FIGURES

FIG. 1 is a block diagram of the vision prosthesis;

FIGS. 2-5 show the vision prosthesis of FIG. 1 implanted at various locations
5 within the eye;

FIGS. 6,7A, and 7B show two embodiments of the lens and actuator of FIG. 1;

FIG. 8 shows a feedback mechanism for a rangefinder of the vision prosthesis of
FIG. 1; and

FIG. 9 shows the vision prosthesis of FIG. 1 mounted on an eyeglass frame.

DETAILED DESCRIPTION

FIG. 1 shows a block diagram of a vision prosthesis 10 having a lens 12 whose
index of refraction can be made to vary in response to a focusing signal provided to the
lens 12 by an actuator 14. The lens 12 directs light through a nematic liquid-crystal
whose index of refraction varies in response to an applied electric field. The actuator 14
15 includes one or more electrodes in electrical communication with the lens 12. However,
the lens 12 can also direct light through a material whose index of refraction varies in
response to an applied magnetic field. In this case, the actuator 14 is a magnetic field
source, such as a current-carrying coil, in magnetic communication with the lens 12.

Throughout this specification, the terms “lens” and “intraocular lens” refer to the
20 prosthetic lens that is part of the vision prosthesis 10. The lens that is an anatomical
structure within the eye is referred to as the “natural lens”.

The nature of the focusing signal provided by the actuator 14 controls the extent
to which the index of refraction is changed. The actuator 14 generates a focusing signal in
response to instructions from a controller 16 in communication with the actuator 14.

25 The controller 16 is typically a microcontroller having instructions encoded
therein. These instructions can be implemented as software or firmware. However, the

instructions can also be encoded directly in hardware in, for example, an application-specific integrated circuit. The instructions provided to the microcontroller include instructions for receiving, from a rangefinder 18, data indicative of the distance to an object-of-regard, and instructions for processing that data to obtain a focusing signal. The focusing signal alters the lens' index of refraction to focus an image of the object-of-regard on the retina.

The rangefinder 18 typically includes a transducer 19 for detecting a stimulus from which a range to an object can be inferred. The signal generated by the transducer 19 often requires amplification before it is of sufficient power to provide to the controller 16. Additionally, the signal may require some preliminary signal conditioning. Accordingly, in addition to a transducer 19, the rangefinder 18 includes an amplifier 21 to amplify the signal, an A/D converter 23 to sample the resultant amplified signal, and a digital signal processor 25 to receive the sampled signal. The output of the digital signal processor 25 is provided to the controller 16.

A power source 20 supplies power to the controller 16, the range finder 18, and the actuator 14. A single power source 20 can provide power to all three components. However, the vision prosthesis 10 can also include a separate power source 20 for any combination of those components that require power.

1. Intraocular vision prosthesis

1.1 Lens and actuator

In one embodiment of the vision prosthesis 10, the lens 12 is an intraocular lens. The intraocular lens 12 can be implanted into an aphakic patient, as shown in FIG. 2, in which case it can be implanted into the lens-bag 22 from which the patient's natural lens has been removed. Alternatively, the intraocular lens 12 can be implanted into a phakic patient, in which case it can be implanted into the posterior chamber 24, between the iris 26 and the patient's natural lens 28, as shown in FIG. 3. With the intraocular lens 12 implanted in the posterior chamber 24, the haptic 30 of the lens 12 rests in the sulcus 32. The intraocular lens 12 can also be implanted in the anterior chamber 34, as shown in FIG. 4, or in the cornea 36, as shown in FIG. 5.

Preferably, the lens **12** is a foldable lens having a tendency to spring back to its unfolded position. Such a lens **12** can be inserted through a small incision, maneuvered into the desired location, and released. Once released, the lens **12** springs back to its unfolded position.

5 In one embodiment of the lens **12**, shown in exploded view in FIG. 6, first and second curved chambers **38a**, **38b** filled with nematic liquid-crystal are separated by a transparent plate **40**. In this embodiment, the actuator **14** includes a variable voltage source **41** connected to two transparent electrodes **42a**, **42b** disposed on an outer surface of each curved chamber **38a**, **38b**. The variable voltage source **41** generates a variable
10 voltage in response to instructions from the controller **16**. First and second transparent outer layers **44a**, **44b** cover the first and second electrodes **42a**, **42b** respectively.

When the variable voltage source **41** applies a voltage, the first and second electrodes **42a**, **42b** impose an electric field in the nematic liquid-crystal. This electric field tends to reorient the directors of the nematic liquid-crystal, thereby changing its
15 index of refraction. A lens assembly of this type is described fully in U.S. Patent No. 4,190,330, the contents of which are herein incorporated by reference.

In another embodiment, shown in FIG. 7A, the lens **12** includes a thin chamber **46** filled with nematic liquid-crystal and the actuator **14** includes a variable voltage source **48** and first and second sets **50a**, **50b** of electrodes **52a-c** disposed on opposed planar
20 surfaces of the thin chamber **46**. Each of the electrodes **52a-c** is individually addressable by the controller **16**. A voltage maintained across a electrode **52a** from the first set **50a** and a corresponding electrode from the second set **50b** results in an electric field across a local zone of the nematic liquid-crystal adjacent to those electrodes. This electric field reorients the directors, and hence alters the index of refraction, within that zone. As a
25 result, the index of refraction can be made to vary at different points of the lens **12**.

FIG. 7A shows a lens assembly having concentric electrodes **52a-c**. A lens assembly of this type is described fully in U.S. Patent No. 4,466,703, the contents of which are herein incorporated by reference. In this embodiment, the index of refraction can be altered as a function of distance from the center of the lens **12**. However,

individually addressable electrodes **52a-c** can also be arranged in a two-dimensional array on the surface of the lens **12**. When this is the case, the index of refraction can be varied as a function of two spatial variables. The grid of electrodes **52a-c** can be a polar grid, as shown in FIG. 7A, or a rectilinear grid, as shown in FIG. 7B. The electrodes **52a-c** can be distributed uniformly on the grid, or they can be distributed more sparsely in certain regions of the lens **12** and more densely in other regions of the lens **12**.

Because of its thin planar structure, a lens **12** of the type shown in FIG. 6 is particularly suitable for implantation in constricted spaces, such as in the posterior chamber **24** of a phakic patient, as shown in FIG. 3.

In another embodiment, the lens **12** includes a chamber filled with a nematic liquid-crystal and the actuator **14** is a current-carrying coil that generates a magnetic field. In this embodiment, the controller **16** causes current to flow in the coil. This current supports a magnetic field that reorients the directors in the nematic liquid-crystal. This results in a change in the liquid crystal's index of refraction.

The extent to which the index of refraction of a nematic liquid crystal can be changed is limited. Once all the directors in the nematic liquid crystal have been polarized, increasing the magnitude of the imposed electric field has no further effect. A nematic liquid crystal in this state is said to be saturated. To change the focal length beyond the point at which the nematic crystal is saturated, a lens **12** can also include one or more lens elements that are moved relative to each other by micromechanical motors.

Alternatively, the lens can have a baseline curvature that and also be filled with nematic crystal. The baseline curvature can be used to perform a gross correction that can be fine-tuned by locally varying the index of refraction of the lens material.

In another embodiment, the lens is made up of a multiplicity of lenslets, as shown in FIG. 7B, each of which has its own baseline curvature and each of which is filled with nematic crystal. An individually addressable electrode is then connected to each of the lenslets. In this embodiment, both the lens curvature and the index of refraction can be varied locally and can be varied as a function of two spatial variables.

1.2 Rangefinder

In a normal eye, contraction of a ciliary muscle **54** is transmitted to the natural lens **28** by zonules⁵⁶ extending between the ciliary muscle **54** and the lens-bag **22**. When the object-of-regard is nearby, the ciliary muscle **54** contracts, thereby deforming the natural lens **28** so as to bring an image of the object into focus on the retina. When the
5 object-of-regard is distant, the ciliary muscle **54** relaxes, thereby restoring the natural lens **28** to a shape that brings distant objects into focus on the retina. The activity of the ciliary muscle **54** thus provides an indication of the range to an object-of-regard.

For an intraocular lens **12**, the transducer **19** of the rangefinder **18** can be a
10 transducer for detecting contraction of the ciliary muscle **54**. In one embodiment, the rangefinder **18** can include a pressure transducer that detects the mechanical activity of the ciliary muscle **54**. A pressure transducer coupled to the ciliary muscle **54** can be a piezoelectric device that deforms, and hence generates a voltage, in response to contraction of the ciliary muscle **54**. In another embodiment, the transducer can include
15 an electromyograph for detecting electrical activity within the ciliary muscle **54**.

As noted above, the activity of the ciliary muscle **54** is transmitted to the natural lens **28** by zonules **56** extending between the ciliary muscle **54** and the lens-bag **22**. Both the tension in the zonules **56** and the resulting mechanical disturbance of the lens-bag **22** can be also be used as indicators of the distance to the object-of-regard. In recognition of
20 this, the rangefinder **18** can also include a tension measuring transducer in communication with the zonules **56** or a motion sensing transducer in communication with the lens-bag **22**. These sensors can likewise be piezoelectric devices that generate a voltage in response to mechanical stimuli.

The activity of the rectus muscles **58** can also be used to infer the distance to an
25 object-of-regard. For example, a contraction of the rectus muscles **58** that would cause the eye to converge medially can suggest that the object-of-regard is nearby, whereas contraction of the rectus muscles **58** that would cause the eye to gaze forward might suggest that the object-of-regard is distant. The rangefinder **18** can thus include a transducer that responds to either mechanical motion of the rectus muscles **58** or to the

electrical activity that triggers that mechanical motion.

It is also known that when a person intends to focus on a nearby object, the iris 26 contracts the pupil 60. Another embodiment of the rangefinder 18 relies on this contraction to provide information indicative of the distance to the object-of-regard. In this embodiment, the rangefinder 18 includes a transducer, similar to that described above
 5 in connection with the rangefinder 18 that uses ciliary muscle or rectus muscle activity, to estimate the distance to the object-of-regard. Additionally, since contraction of the pupil 60 diminishes the light incident on the lens 12, the transducer 19 of the rangefinder 18 can include a photodetector for detecting this change in the light.

10 The foregoing embodiments of the rangefinder 18 are intended to be implanted into a patient, where they can be coupled to the anatomical structures of the eye. This configuration, in which the dynamic properties of one or more anatomical structures of the eye are used to infer the distance to an object-of-regard, is advantageous because those properties are under the patient's control. As a result, the patient can, to a certain
 15 extent, provide feedback to the rangefinder 18 by controlling those dynamic properties. For example, where the rangefinder 18 includes a transducer responsive to the ciliary muscle 54, the patient can control the index of refraction of the intraocular lens 12 by appropriately contracting or relaxing the ciliary muscle 54.

Other embodiments of the rangefinder 18 can provide an estimate of the range
 20 without relying on stimuli from anatomic structures of the eye. For example, a rangefinder 18 similar to that used in an auto-focus camera can be implanted. An example of such a rangefinder 18 is one that transmits a beam of infrared radiation, detects a reflected beam, and estimates range on the basis of that reflected beam. The output of the rangefinder 18 can then be communicated to the actuator 14. Since a
 25 rangefinder 18 of this type does not rely on stimuli from anatomic structures of the eye, it need not be implanted in the eye at all. Instead, it can be worn on an eyeglass frame or even hand-held and pointed at objects of regard. In such a case, the signal from the rangefinder 18 can be communicated to the actuator 14 either by a wire connected to an implanted actuator 14 or by a wireless link.

A rangefinder **18** that does not rely on stimuli from an anatomic structure within the eye no longer enjoys feedback from the patient. As a result, it is desirable to provide a feedback mechanism to enhance the range-finder's ability to achieve and maintain focus on an object-of-regard.

5 In a feedback mechanism as shown in FIG. 8, first and second lenslets **62a**, **62b** are disposed posterior to the intraocular lens **12**. The first and second lenslets **62a**, **62b** are preferably disposed near the periphery of the intraocular lens **12** to avoid interfering with the patient's vision. A first photodetector **64a** is disposed at a selected distance posterior to the first lenslet **62a**, and a second photodetector **64b** is disposed at the same
10 selected distance posterior to the second lenslet **62b**. The focal length of the first lenslet **62a** is slightly greater than the selected distance, whereas the focal length of the second lenslet **62b** is slightly less than the selected distance.

 The outputs of the first and second photodetectors **64a**, **64b** are connected to a differencing element **66** that evaluates the difference between their output. This
15 difference is provided to the digital signal processor **25**. When the output of the differencing element **66** is zero, the intraocular lens **12** is in focus. When the output of the differencing element **66** is non-zero, the sign of the output identifies whether the focal length of the intraocular lens **12** needs to be increased or decreased, and the magnitude of the output determines the extent to which the focal length of the intraocular lens **12** needs
20 to change to bring the lens **12** into focus. A feedback mechanism of this type is disclosed in U.S. Patent No. 4,309,603, the contents of which are herein incorporated by reference.

 In any of the above embodiments of the rangefinder **18**, a manual control can also be provided to enable a patient to fine-tune the focusing signal. The digital signal processor **25** can then use any correction provided by the user to calibrate the range
25 estimates provided by the rangefinder **18** so that the next time that that range estimate is received, the focusing signal provided by the digital signal processor **25** will no longer need fine-tuning by the patient. This results in a self-calibrating vision prosthesis **10**.

 The choice of which of the above range-finders is to be used depends on the particular application. For example, a lens **12** implanted in the posterior chamber **24** has

ready access to the ciliary muscle **54** near the haptic **30** of the lens **12**. Under these circumstances, a rangefinder that detects ciliary muscle activity is a suitable choice. A lens **12** implanted in the anterior chamber **34** is conveniently located relative to the iris **26** but cannot easily be coupled to the ciliary muscle **54**. Hence, under these circumstances, a rangefinder that detects contraction of the iris **26** is a suitable choice. A lens **12** implanted in the cornea **36** is conveniently located relative to the rectus muscles **58**. Hence, under these circumstances, a rangefinder that detects contraction of the rectus muscles **58** is a suitable choice. In the case of an aphakic patient, in which the natural lens **28** in the lens-bag **22** has been replaced by an intraocular lens **12**, a rangefinder that detects zonule tension or mechanical disturbances of the lens-bag **22** is a suitable choice. In patients having a loss of function in any of the foregoing anatomical structures, a rangefinder that incorporates an automatic focusing system similar to that used in an autofocus camera is a suitable choice.

1.3 Power source

As noted above, the controller **16**, the rangefinder **18**, and the actuator **14** shown in FIG. 1 require a power source **20**. In one embodiment, the power source **20** can be an implanted battery **68**. The battery **68** can be implanted in any convenient location, such as under the conjunctiva **70** in the Therron's capsule, or within the sclera. Unless it is rechargeable in situ, such a power source **20** will periodically require replacement.

In another embodiment, the power source **20** can be a photovoltaic cell **72** implanted in a portion of the eye that receives sufficient light to power the vision prosthesis **10**. The photovoltaic cell **72** can be mounted on a peripheral portion of the lens **12** where it will receive adequate light without interfering excessively with vision. Alternatively, the photovoltaic cell **72** can be implanted within the cornea **36**, where it will receive considerably more light. When implanted into the cornea **36**, the photovoltaic cell **72** can take the form of an annulus or a portion of an annulus centered at the center of the cornea **36**. This configuration avoids excessive interference with the patient's vision while providing sufficient area for collection of light.

Power generated by such a photovoltaic cell **72** can also be used to recharge a

battery 68, thereby enabling the vision prosthesis 10 to operate under low-light conditions. The use of a photovoltaic cell as a power source 20 eliminates the need for the patient to undergo the invasive procedure of replacing an implanted battery 68.

The choice of a power source 20 depends in part on the relative locations of the components that are to be supplied with power and the ease with which connections can be made to those components. When the lens 12 is implanted in the cornea 36, for example, the associated electronics are likely to be accessible to a photovoltaic cell 72 also implanted in the cornea 36. In addition, a rechargeable subconjunctival battery 68 is also easily accessible to the photovoltaic cell 72. The disposition of one or more photovoltaic cells 72 in an annular region at the periphery of the cornea 36 maximizes the exposure of the photovoltaic cells 72 to ambient light.

When the lens 12 is implanted in the anterior chamber 34, one or more photovoltaic cells 72 are arranged in an annular region on the periphery of the lens 12. This reduces interference with the patient's vision while providing sufficient area for exposure to ambient light. For a lens 12 implanted in the anterior chamber 34, a rechargeable battery 68 implanted beneath the conjunctiva 70 continues to be conveniently located relative to the photovoltaic cells 72.

When the lens 12 is implanted in the posterior chamber 24, one or more photovoltaic cells 72 can be arranged in an annular region of the lens 12. However, in this case, the periphery of the lens 12 is often shaded by the iris 26 as it contracts to narrow the pupil 60. Because of this, photovoltaic cells 72 disposed around the periphery of the lens 12 may receive insufficient light to power the various other components of the vision prosthesis 10. As a result, it becomes preferable to dispose the photovoltaic cells 72 in an annular region having radius small enough to ensure adequate lighting but large enough to avoid excessive interference with the patient's vision.

2. Extraocular vision prosthesis

The lens 12 in FIG. 1 need not be an intraocular lens. In an alternative embodiment, shown in FIG. 9, the vision prosthesis 10, including the lens 12, is mounted on a frame 74 and worn in the manner of conventional eyeglasses. This embodiment

largely eliminates those constraints on the size and location of the power source **20** that are imposed by the relative inaccessibility of the various anatomical structures of the eye as well as by the limited volume surrounding them.

5 In the embodiment shown in FIG. 9, the rangefinder **18** is typically of the type used in an autofocus camera together with the two-lenslet feedback mechanism described above in connection with the intraocular vision prosthesis **10**. The lens **12**, its associated actuator **14**, and the power source **20** can be selected from any of the types already described above in connection with the intraocular embodiment of the vision prosthesis **10**.

10 It is to be understood that while the invention has been described in conjunction with the detailed description thereof, the foregoing description is intended to illustrate and not limit the scope of the invention, which is defined by the scope of the appended claims. Other aspects, advantages, and modifications are within the scope of the following claims.

15 Having described the invention, and a preferred embodiment thereof, what I claim as new and secured by letters patent is: